# **Manipulation approaches for Ensemble Learning**

- instance
- feature
- algorithm
- class label

## **Ensemble Methods**

- stacking
- bagging
  - random forest
- boosting
  - AdaBoost

# Stacking

• idea: smooths errors over range of algorithms with different biases

## Simple voting

- generate multiple training datasets through different feature subsets
- train base classifier over each dataset
- presupposes classifiers have equal performance

## **Meta classification**

- train a classifier over output of base classifiers
- train using nested cross validation to reduce bias
- e.g. Level 0: given training dataset (X, y):
  - train NN
  - train NB
  - train DT
- (possibly) discard X, and add new attributes for each instance

- prediction of classifier above
- other data as available (NB scores)
- Level 1: train meta-classifier
  - usually logistic regression or neural network

#### **Nested cross-validation**

- need to prevent testing  $L_1$  classifier on same data as  $L_0$  classifiers trained on
- cross-validate base models on a subset of the folds
- cross-validate meta-classifier on all the folds
- Nested Cross Validation

#### Assessment

- mathematically simple
- computationally expensive
- can combine heterogeneous classifiers with varying performance
- generally produces  $\geq$  results than best base classifier
- widely used in applied research, less interest in theoretical circles
  - few guarantees, but empirically good performance

#### Bagging

- bootstrap aggregation
- idea: more data means better performance (lowering variance)
  - how can we get more data out of a fixed training dataset?
- method: construct novel dataset through random sampling and replacement
  - **bootstrap:** randomly sample original dataset N times with replacement
  - gives new dataset of same size. Probability any individual instance is absent is  $\approx 37\%$  for large N
  - construct k random datasets for k bae classifiers
  - prediction via voting
- **Random sampling with replacement:** when instance selected from population at random is returned to population before next element is sampled

- each sample value is independent: what we get the second time has no dependence on what we got the first time
- cf. without replacement: you won't get repetition of any elements; two samples aren't independent

## Assessment

- the same weak base classifier used throughout
- as bagging is aimed towards minimising variance through sampling, the algorithm should be unstable (high-variance)
- so use it with more complex models e.g. decision trees
- bagging **cannot** reduce bias
- simple method: sampling + voting
- can parallelise computation of individual base classifiers
- highly effective over noisy datasets: outliers may vanish
- performance generally significantly better than base classifiers, but occasionally substantially worse

## **Random Forest**

#### **Random tree**

- feature manipulation
- decision tree, where
  - at each node, only some of possible attributes considered
  - e.g. fixed proportion of all unused attributes
  - attempts to control for unhelpful attributes in feature set
  - faster to build than deterministic decision tree, but has higher model variance

## **Random forest**

- bagging method
- ensemble of random trees
- each tree is built using a different bagged training dataset
- combined classification via voting
- · idea: minimise overall model variance, without introducing combined model bias
- instance manipulation

#### **Ensemble Methods**

#### • hyperparameters:

- number of trees B: can be tuned, e.g. 100
- feature sub-sample size often  $(\log |F| + 1)$
- loss of interpretability
  - logic behind individual instances can be followed for individual trees
  - logic of overall model is unclear

## Assessment

- generally strong performer
- parallelisable
- surprisingly efficient
- robust to overfitting
- loss of interpretability

# Boosting

- idea: tune base classifiers to focus on difficult instances (i.e. those hard to classify)
- approach: iteratively change the distribution and weights of training instances to reflect performance of classifier at previous iteration
  - start with each training instance having uniform probably of inclusion in the sample
  - over *T* iterations, train a classifier. **Update the weight** of each instance according to whether it was correctly classified
  - combine base classifiers via weighted voting

# AdaBoost

- Adaptive Boosting
- sequential ensembling algorithm
- base classifier: C<sub>0</sub>
- training instances:  $\{(x_j,y_j)|j=1,...,N\}$
- initial instance weights:  $w_i^0 = \frac{1}{N}$
- in iteration *i*:
  - construct classifier  $C_i$

– compute error rate  $\epsilon_i$ 

$$\epsilon_i = \sum_{j=1}^N w^i_j \delta(C_i(x_j) \neq y_j)$$

- use  $\epsilon_i$  to compute **classifier weight**  $\alpha_i$  importance of classifier  $C_i$ 
  - \* low error means high classifier weight
- use  $\alpha_i$  to update **instance weights**
- add weighted  $C_i$  to ensemble

Output: weighted set of base classifiers:  $\{(\alpha_1, C_1), ..., (\alpha_T, C_T)\}$ 

# $\operatorname{Computing} \alpha$

- importance of  $C_i,$  the weight associated with  $C_i\,{}^{\prime}\!{\rm s}$  vote

$$\alpha_i = \frac{1}{2} \ln \frac{1 - \epsilon_i}{\epsilon_i}$$

• this is derived via minimisation of error



# Figure 1: alpha

- when error is low,  $\alpha$  is high
- random classifier has  $\epsilon=0.5$ , so if error is greater than this (lpha<0), re-initialise

# $\mathbf{Updating}\,w$

- weights for instance j at iteration i + 1
- if  $C_i(\boldsymbol{x}_i) = y_i$  , correct prediction, so decrease weight for next iteration:

$$w_j^{i+1} = \frac{w_j^i}{Z_i} \exp{-\alpha_j}$$

- if  $C_i(x_i) \neq y_i$ , incorrect prediction, so increase weight for next iteration:

$$w_j^{i+1} = \frac{w_j^i}{Z_i} \exp \alpha_i$$

+  $\, Z_i$  is a normalisation constant such that  $\sum w_j = 1 \,$ 



Figure 2: weight update

- iterate for i = 1, ..., T
- reinitialise instance weights whenever  $\epsilon_i < 0.5$

# Classification

• classification by weighted vote

$$C^*(x) = \operatorname*{arg\,max}_y \sum_{j=1}^T \alpha_j \delta(C_j(x) = y)$$

#### Assessment

- mathematically complicated, computationally cheap
- iterative sampling + weighted voting
- more expensive than bagging
- as long as each base classifier is better than random, convergence to a stronger model is guaranteed
- guaranteed performance error bounds over training data
- · decision stumps/decision trees typically used as base classifiers. Extremely popular
- has a tendency to overfit
- gradient boosting is another more recent boosting approach

# **Bagging vs Boosting**

## Bagging

- parallel sampling
- simple voting
- homogeneous base classifiers
- minimises variance
- not prone to overfitting

#### Boosting

- iterative sampling
- weighted voting
- homogeneous base classifiers
- minimises instance bias
- prone to overfitting